#### **CAMBRIDGE INTERNATIONAL EXAMINATIONS**

Cambridge International Advanced Subsidiary and Advanced Level

## MARK SCHEME for the March 2016 series

# 9702 PHYSICS

9702/52

Paper 5 (Planning, Analysis and Evaluation), maximum raw mark 30

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## 1 Planning (15 marks)

## **Defining the problem (2 marks)**

- P k is the independent variable and h is the dependent variable, or vary k, measure h. [1]
- P Keep mass of object constant. [1]

## Methods of data collection (4 marks)

- M Labelled diagram (minimum two labels) showing object (mass) attached to cord <u>and</u> other end of cord fixed (e.g. stand and clamp or hook) <u>and</u> rule(r) drawn vertically next to cord. [1]
- M Method of measuring mass e.g. balance/scales. [1]
- M k = (weight or force)/extension or mg/extension; allow graphical methods.Allow any subject e.g.  $mg = k \times \text{extension}.$
- M Use of rule to measure h or maximum distance/length (fallen by the object).
  Allow clear indication on diagram (i.e. dotted lines) linking distance h to rule.
  Do not credit length of cord.

## Method of analysis (3 marks)

✓ Plot a graph of 
$$\frac{(h-L)^2}{h}$$
 against  $1/k$  [Allow  $2/k$  or  $2m/k$  or  $m/k$ ] [1]

- ✓ g = gradient/2m [gradient/ m or gradient or gradient/2] [1]
- ✓ Relationship is valid if the graph is a straight line passing through the origin. [1]

#### Additional detail (6 marks)

- D Relevant points [6]
- 1 Keep starting point constant/drop object from same position/use of electromagnet to drop object/ensure mass is dropped from fixed point/check object falls vertically
- 2 Rule(r) fixed e.g. retort stand
- Method to determine extension, e.g. <u>measure</u> length of stretched cord and subtract original length/50.0 cm. [Accept from a diagram]
- 4 Safety precaution linked to prevention of mass/cord hitting a person use safety screen/goggles; sand tray to catch falling object if cord breaks
- 5 Trial experiment to locate approximate point of h/to prevent object hitting surface
- 6 Detailed use of video camera with slow motion or frame by frame playback/motion sensor clearly explained
- 7 Cord obeys Hooke's law or must not exceed elastic limit
- 8 Use set square to ensure ruler is vertical
- 9 For each cord, repeat experiment determine average h

Do not allow vague computer methods.

[Total: 15 marks]

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# 2 Analysis, conclusions and evaluation (15 marks)

Part	Mark	Expected Answer
(a)	A1	Gradient = $\frac{c_m \Delta \theta}{P}$ y-intercept = $\frac{m_w c_w \Delta \theta + k}{P}$
(b)	T1	Column heading <i>m</i> <sub>m</sub> /g 100 200 300 400 500 600
	U1	From ± 10 to ± 60
(c)(i)	G1	Six points plotted correctly
	U2	Error bars in $m_{\rm m}$ plotted correctly
(ii)	G2	Line of best fit
	G3	Worst acceptable straight line. Steepest or shallowest possible line that passes through <u>all</u> the error bars.
(iii)	C1	Gradient of best fit line
	U3	Difference in worst gradient and gradient.
(iv)	C2	y-intercept
	U4	Uncertainty in <i>y</i> -intercept
(d)(i)	C3	$c_m$ in the range 470 to 530 <u>and</u> given to 2 or 3sf
	C4	$k = y$ -intercept x $P - m_w c_w \Delta \theta$ k = y-intercept x 50 - 21000
	C5	Units for $c_m$ and $k$
(ii)	U5	Percentage uncertainty in $C_m$

[Total: 15 marks]

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## **Uncertainties in Question 2**

## (c) (iii) Gradient [U3]

- 1 Uncertainty = gradient of line of best fit gradient of worst acceptable line
- 2 Uncertainty = ½ (steepest worst line gradient shallowest worst line gradient)

## (iv) [U4]

- 1 Uncertainty = y-intercept of line of best fit y-intercept of worst acceptable line
- 2 Uncertainty =  $\frac{1}{2}$  (steepest worst line *y*-intercept shallowest worst line *y*-intercept)

### (d) (ii) [U5]

1 %uncertainty = 
$$\left(\frac{\Delta gradient}{gradient} + \frac{5}{50} + \frac{0.5}{20}\right) x 100 = \left(\frac{\Delta gradient}{gradient}\right) x 100 + 12.5\%$$

$$2 \quad \max c_m = \frac{\max gradient \times \max power}{\min temperature change} = \frac{\max gradient \times 55}{19.5}$$

3 
$$\min c_m = \frac{\min gradient \ x \ min \ power}{\max temperature \ change} = \frac{\min gradient \ x \ 45}{20..5}$$